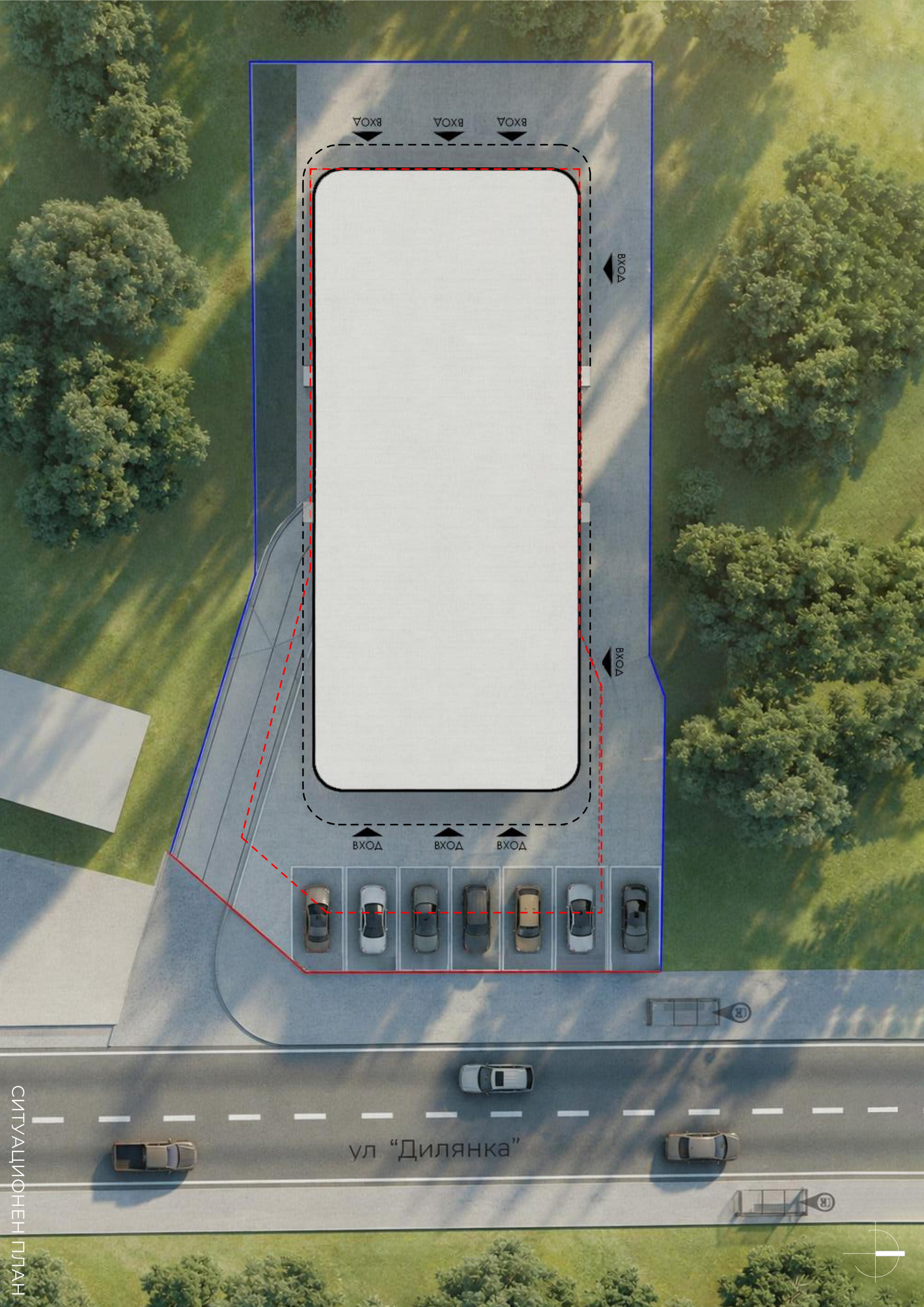

СИТУАЦИОНЕН ПЛАН

РАЗПРЕДЕЛЕНИЕ КОТА ±0.00